# **Goodrive20 Series**

Vector Control Inverter

Your Trusted Industry Automation Solution Provider







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Industrial Automation:

Frequency Inverter

• Servo & Motion Control

• Motor & Electric Spindle

• Traction Drive

• PLC

Electric Power: • SVG

• HMI Solar Inverter

Intelligent Elevator Contral System

Online Energy Management System

New Energy Vehicle Electric Control System

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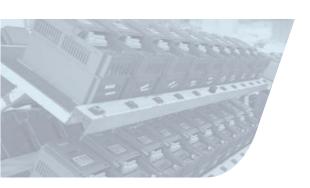


# / Introduction

Goodrive20 series inverters feature excellent drive and control performance for using of sensorless vector control technology, and improve usability and reliability for the enriched hardware configurations and software functions, meeting different industrial applications.









# / Features

# Optimized structure design

Optimized spare utilization, models (≥18.5kW) is much smaller than existing inverters.

#### Size compared with GD200A

Power Rate	Size of GD20 (W*H*D)	Size of GD200A (W*H*D)	Size decreased than GD200A
18.5kW	200*340.6*184.3	230*342*216	26%
22kW	200*340.6*184.3	255*407*245	51%
30kW	250*400*202	255*407*245	21%
37kW	250*400*202	270*555*325	59%
45kW	282*560*238	270*555*325	23%
55kW	282*560*238	270*555*325	23%
75~110kW	338*554*329.2	325*680*365	24%

Mini design for inverters (≤ 2.2kW); abreast installation of multiple inverters, reducing installation space



Flexible installation ways





Rail mounting



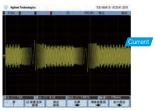


Wall mounting



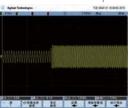
# **Excellent Performance**

### Excellent vector control performance

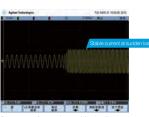


Current waveforms in vector control mode with 50Hz and full load

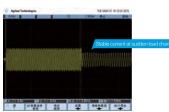
#### Excellent motor drive performance



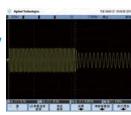
Current waveforms when sudden loading in V/F control mode with 2Hz and full load



Current waveforms when sudden loading in vector control mode with 0.5Hz and full load

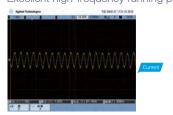


Current waveforms when sudden unloading in V/F control mode with 2Hz and full load

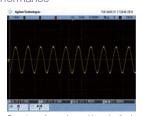


Current waveforms when sudden unloading in vector control mode with 0.5Hz and full load

### Excellent high-frequency running performance



Current waveforms when sudden loading in vector control mode with 0.5Hz and full load



Current waveforms when sudden unloading in vector control mode with 0.5Hz and full load

# Multi-function and easy to use

DC reactors are built-in inverters ≥18.5kW



The braking unit is built-in and standard for inverters ≤37kW but optional for inverters of 45-110kW.

Dynamic braking can be implemented by only configuring braking resistors, reducing occupation space.



Compared about embedded braking unit

Inverters (380V; ≥4kw) support the DC bus sharing solution.

Dynamic braking can be implemented by only configuring braking resistors, reducing occupation space.



### Built-in Safety Torque Off function

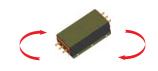
GD20 series inverter support Built-in Safety Torque Off function, and passed the certification as followed:

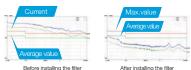
Model	Certification standard and grade								
Wodel	IEC 6	1508	EN/ISO	13849-1	EN954-1				
-S2:0.4~2.2kW -2:0.4~0.75kW -4:0.75~2.2kW	SIL	2	PL	d	Category	3			
-2:1.5~7.5kW -4:4~110kW	SIL	3	PL	е	Category	3			

### C3 and C2 filters

C3 filters are built in inverters (3PH; 380V; ≥4kW) and (3PH; 220V; ≥1.5kW) by using J10 to determine the connection or disconnection. External C3 filters can be configured for inverters (1PH; 220V; ≤2.2kW), (3PH; 380V; ≤2.2kW) and (3PH; 220V; ≤0.75kW).

External C2 filters are optional for all GD20 series inverters.





Conductive interference test of the power supply terminals

#### Remarks:

C2 filter: EMC performance of the inverter achieves the limited usage requirement in civil environment.

C3 filter: EMC performance of the inverter achieves the limited usage requirement in industrial environment.

# Support of external keypad

The membrane keypad are standard for inverters (380V;  $\leqslant$  2.2kW), which also support external LED keypads. The keypads for inverters (3PH; 380V;  $\geqslant$ 4kW) can be used as external keynads

GD20 series inverters can be configured with LED keypad which has the data copy function to upload or download the parameters.



Pluggable design for cooling fans, making maintenance easy



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# Abundant software functions

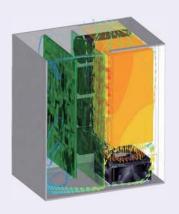
Function	Used to	Remarks
RS485 communication	Read and modify inverter parameters through connection to the upper computer so as to control inverter running status.	Configured with RS485 communication interface
PID	Carry out PID operation on feedback signals to control inverter output frequency and improve target accuracy and stability. Applicable to presence, flow and temperature process control.	Supports PID output polarity switching.
Motor parameter autotuning	Carry out rotation or static autotuning, improving control accuracy and response speed.	Classified into rotation autotuning and static autotuning.
Simple PLC function	Change the running frequency and direction automatically according to the running time set by simple PLC to meet process requirements.	Supports multiple running modes.
Multi-step speed control	Meet the speed control requirements in different periods of time.	A maximum of 16 steps can be divided for multi-step speed control.
Multiple V/F curve settings	Meet the requirements of energy-saving operation for fans and water pumps and of various variable frequency power supplies; adapt to different load applications.	Linear, multi-dot, multi-power and V/F separation settings, implementing flexible setting of V/F curves.
Virtual terminals	Take external signals as local virtual I/O to reduce hardware configuration.	Corresponding virtual terminal functions must be enabled in communication mode.
Delay of switching on and off	Provide more programming and control modes	Max. switching on/off delay is 50s
Uninterrupted running in instantaneous power off	Ensure uninterrupted running in instantaneous power off. Especially applicable to the situations with high requirements on continuous operation.	At transient voltage drop, the inverter can keep running by feedback energy without stop in valid time.
Various protection functions	Provide overall fault protection functions.	Various measures provided to protect against faults such as overcurrent, overvoltage, undervoltage, overheating, and overload, whose information can be saved.
Multiple braking modes available	Provide multiple braking modes, satisfying accurate and quick stop under different loads.	DC braking, flux braking, dynamic braking
Battery capacity display	Display the accumulative power consumption on the inverter without watthour meter.	Inverter power consumption can be queried.

# Reliable QA

Goodrive20 is designed follow the IEC standards and passes the CE test.



Exact thermal design is made based on advanced thermal technology.



# Perfect and Reliable Test System Ensure Products Adapt Complicated Site Environments and Achieved ACT Certificate of TÜV SÜD

Experiment Type	Experiment Name	Classification
		Package compression experiments
		Package Resonance imaging and storage test
		Package random vibration test
	Packaging Experiments	Package dropping test
		Package rolling test
Mechanical Reliability Experiments		Package dumping test
		Package inclined impact test
	Impact Test	Half-sine shock test(working and non-working state)
	impact rest	Trapezoidal wave impulse test(non-working state)
		Sinusoidal vibration test(working state)
	Vibration Test	Random vibration test(working and non-working state)
		Low temperature storage test
		High temperature storage test
	Temperature	Low temperature working test
	Experiment	High temperature working test
		Gradient temperature change test
Climatic Environmental		Temperature impact test
Reliability Test	Temperature	Constant temperature & humidity test
	Humidity Test	Alternation temperature & humidity test
	Salt Spray Test	Constant salt spray test
		Alternation salt spray test
	Low Air	Combined dry heat & low air pressure test
	Pressure Test	Combined cold & low air pressure test

#### Remarks

The full name of ACT is Acceptance of Client's Testing, which means the German TÜV SÜD admit the technology level of the lab and accept their separate testing data and test reports officially.



Electric Vibration System



Low Prssure Test Chamber& Constant temperature and humidity test chamber



Faster temperature chamber& Thermal Shock Test Chamber

# / Applications





















# / Technical specification

Power input   Input voltage (V)   SPH 250V (-15%) -240V (-10%) SPH 360V (-15%) -440V (-10%) SPH 360V (-10		Function	Specification		
Input frequency (Hz)   Feler to the rated value	Power input	Input voltage (V)	3PH 220V(-15%)~240V(+10%)		
Power output  Output current (A) Output voltage (V) Output frequency (Hz) O-input voltage, error-5% O-400Hz SPPWM, SVC Adjustable-speed ratio 1:100 Speed control accuracy 4:0.2% (SVC) Speed fluctuation Torque response 2-20ms (SVC) Torque control accuracy 10% Starting torque Overload capability Dioside of tated current: 1 minute 150% of rated current: 1 minute 150% of rated current: 1 seconds 20% of rated current: 1 seconds 20% of rated current: 10 seconds 20% of rated current: 1 seconds 20% of rated current: 10 seconds 20% of	rower input	Input current (A)	Refer to the rated value		
Power output		Input frequency (Hz)	50Hz or 60Hz, allowed range: 47~63Hz		
Output voltage (V)		Output motor capacity (kW)	Refer to the rated value		
Output rollage (V) Output frequency (Hz) Adjustable-speed ratio Speed control accuracy \$0.2% (SVC) Speed ductuation \$0.2% (SVC) Speed functuation \$0.5Hz/150% (SVC) Torque rontrol accuracy \$1.0% Starting torque Overload capability Overload capability  Digital setting, analog setting, pulse frequency setting, multi-step speed running setting, smiple PLC setting, PID setting, MODBUS communication setting Shift between the set combination and set channel.  Keep a stable voltage automatically when the grid voltage transients Fault protection Fault protection Fault protection (Al2) 0–10V/0–20mA and 1 (Al3) -10–10V Analog input 1 (Al2) 0–10V/0–20mA and 1 (Al3) -10–10V Digital input Digital output 1 (Y terminal output; the Max. frequency; 50kHz Digital output 1 Y terminal output; the Max. frequency; 50kHz Shift protection (Al2) 0–10V/0–20mA and 1 (Al3) -10–10V Contactor capacity; 3AA/AC250V Mountable method Wall and rail mountable Braking unit Embedded EMI filter Digital output Fineperature of the running environment. Altitude Altitude Frotective degree Safety Meet the requirement of CE	Danier autout	Output current (A)	Refer to the rated value		
Control mode	rower output	Output voltage (V)	0~input voltage, error<5%		
Adjustable-speed ratio Speed control accuracy \$0.2% (SVC) \$peed fluctuation \$1.3% (SVC) \$1.3% (SVC) \$1.50% (SVC) \$1.50% (SVC) \$1.50% of rated current: 1 minute \$1.80% of rated current: 1 minute \$1.80% of rated current: 1 seconds \$2.00% (SVC) \$1.50% of rated current: 1 seconds \$2.00% of rated current: 1 minute \$2.00% of		Output frequency (Hz)	0~400Hz		
Speed control accuracy   ±0.2% (SVC)		Control mode	SVPWM, SVC		
Speed fluctuation		Adjustable-speed ratio	1:100		
Technical control feature  Torque control accuracy Torque control accuracy 10% Starting torque 0. 5Hz/150% (SVC) 150% of rated current: 1 minute 180% of rated current: 10 seconds 200% of rated current: 10 secon		Speed control accuracy	±0.2% (SVC)		
Torque control accuracy  Starting torque  O. 5Hz/150% (SVC)  Overload capability  Overload capability  Trequency setting method  Frequency setting method  Frequency setting method  Digital setting, analog setting, pulse frequency setting, multi-step speed running setting, simple PLc setting, PID setting, MODBUS communication setting setting, simple PLc setting, PID setting, MODBUS communication setting setting, simple PLc setting, PID setting, MODBUS communication setting setting, simple PLc setting, PID setting, MODBUS communication setting setting, simple PLc setting, PID setting, MODBUS communication setting setting, simple PLc setting, PID setting, MODBUS communication setting setting, simple PLc setting, PID setting, MODBUS communication setting setting, simple PLc setting, PID setting, MODBUS communication setting setting, simple PLc setting, PID setting, MODBUS communication setting, setting, pill setting, MODBUS commonication setting, setting, pill setting, MODBUS commonication setting, setting, pill setting, pill setting, MODBUS commonication, setting, pill setting, MODBUS co		Speed fluctuation	± 0.3% ( SVC)		
Starting torque  O. 5Hz/150% ( SVC)  Overload capability  Digital setting, analog setting, pulse frequency setting, multi-step second s	Technical control feature	Torque response	<20ms (SVC)		
Digital control feature   Superior Community   Digital setting analog setting, pulse frequency setting method   Digital setting, analog setting, pulse frequency setting, multi-step speed running setting, simple PLC setting, PID setting, MODBUS communication setting simple PLC setting, PID setting, MODBUS communication setting shift between the set combination and set channel.   Reep a stable voltage automatically when the grid voltage transients   Provide comprehensive fault protection functions: over-current, over-voltage, under-voltage, over-heating, phase loss and overload, etc.   Analog input   1 (AI2) 0-10V/0-20mA and 1 (AI3) -10-10V   Analog output   2 (AO1, AO2) 0-10V/0-20mA and 1 (AI3) -10-10V   Digital input   1 yet terminal output;   1 high speed input, the Max. frequency: 1kHz;   1 high speed input, the Max. frequency: 50kHz   1 yet reminal output;   2 programmable relay outputs   Relay output   Relay output   Ro1A NO, RO1B NC, RO1C common terminal RO2A NO, RO2B NC, RO2C common terminal RO2A NO, RO2B NC,		Torque control accuracy	10%		
Digital control feature   Second   Se		Starting torque	0. 5Hz/150% ( SVC)		
Frequency setting method speed running setting, simple PLC setting, PID setting, MODBUS communication setting Shift between the set combination and set channel.  Auto-adjustment of the voltage Keep a stable voltage automatically when the grid voltage transients  Fault protection Provide comprehensive fault protection functions: over-outrent, over-voltage, over-heating, phase loss and overload, etc.  Analog input 1 (AI2) 0-10V/0-20mA and 1 (AI3) -10-10V  Analog output 2 (AO1, AO2) 0-10V/0-20mA with the Max. frequency: 1kHz; 1 high speed input, the Max. frequency: 50kHz  Digital input 1 1 Y1 terminal output;  Relay output 2 programmable relay outputs  Relay output 3 programmable relay outputs  Ro1A NO, RO1B NO, RO2C common terminal RO2A NO, RO2B NO, RO2C common terminal RO2A NO, RO3B NO, RO3C common terminal RO3A NO, RO3B NO, RO3C common terminal RO3A NO, RO3B NO, RO3C common terminal RO3A NO, RO3C		Overload capability	180% of rated current: 10 seconds		
Fault protection transients  Fault protection Provide comprehensive fault protection functions: over-current, over-voltage, under-voltage, over-heating, phase loss and overload, etc.  Analog input 1 (Al2) 0-10V/0-20mA and 1 (Al3) -10-10V  Analog output 2 (AO1, AO2) 0-10V/0-20mA and 1 (Al3) -10-10V  Digital input 3 4 common inputs, the Max. frequency: 1kHz; 1 high speed input, the Max. frequency: 50kHz  Digital output 1 1 Y1 terminal output;  Relay output 2 programmable relay outputs  Rola NO, RO1B NC, RO1C common terminal RO2A NO, RO2B NC, RO2C common terminal RO2A NO, RO3B NC, RO3C common terminal RO3A NO, RO3C common terminal RO3A NO, RO3B NC, RO3C common terminal RO3A N		Frequency setting method	speed running setting, simple PLC setting, PID setting, MODBUS communication setting		
Peripheral interface	Running control feature	Auto-adjustment of the voltage	Keep a stable voltage automatically when the grid voltage transients		
Analog output 2 (AO1, AO2) 0-10V/0-20mA  Digital input 4 common inputs, the Max. frequency: 1kHz; 1 high speed input, the Max. frequency: 50kHz  1 y1 terminal output;  Relay output 2 programmable relay outputs RO1A NO, RO1B NG, RO1C common terminal RO2A NO, RO2B NG, RO2C common terminal RO2A NO, RO3B NG, RO2C common terminal RO2A NO, RO3B NG, RO2C common terminal RO2A NO, RO2B NG, RO2C common terminal RO2A NO, RO2B NG, RO2C common terminal RO2A NO, RO2B NG, RO2C common terminal RO2A NO, RO3B NG, RO2C common terminal RO2A NO, RO2B NG, RO2C common terminal RO2B NG, RO2C common terminal RO2B NG, RO2		Fault protection	over-voltage, under-voltage, over-heating, phase loss and overload		
Digital input  Digital input  Digital output  1 Y1 terminal output;  Relay output  Relay output  Mountable method  Braking unit  Embedded  EMI filter  Embedded  Dipital Output  Temperature of the running environment  Altitude  Protective degree  Safety  Meet the requirement of CE		Analog input	1 (Al2) 0~10V/0~20mA and 1 (Al3) -10~10V		
Peripheral interface  Digital output  1 high speed input, the Max. frequency: 50kHz  1 Y1 terminal output;  Pelay output  Relay output  Relay output  Mountable method  Braking unit  Embedded  EMI filter  Discoration and filter: meet the degree requirement of IEC61800-3 C2, IEC61800-3 C3  Temperature of the running environment  Altitude  Altitude  Protective degree  Safety  Meet the requirement of CE		Analog output	2 (AO1, AO2) 0~10V/0~20mA		
Polytate output  1 Y1 terminal output;  2 programmable relay outputs Ro1A NO, RO1B NC, RO1C common terminal RO2A NO, RO2B NC, RO2C common terminal RO2A NO, RO2C common terminal RO2A NO, RO2C Common terminal RO2A NO, RO2C RO2C RO2C RO2C RO2C RO2C RO2C RO2C		Digital input			
Relay output RO1A NO, RO1B NG, RO1C common terminal RO2A NO, RO2B NG, RO2C common terminal RO2A NO, RO2B NG, RO2B NG RO2B N	Peripheral interface	Digital output	1 Y1 terminal output;		
Braking unit Embedded  EMI filter Optional filter: meet the degree requirement of IEC61800-3 C2, IEC61800-3 C3  Temperature of the running environment -10-50°C Abows 40°C, derate 1% for every additional 1°C.  Altitude -1000m Above 1000m, derate 1% for every additional 100m.  Protective degree IP20  Safety Meet the requirement of CE		Relay output	RO1A NO, RO1B NO, RO1C common terminal RO2A NO, RO2B NC, RO2C common terminal		
Optional filter: meet the degree requirement of IEC61800-3 C2, IEC61800-3 C3  Temperature of the running environment above 40°C, derate 1% for every additional 1°C.  Altitude <1000m Above 40°C, derate 1% for every additional 100m.  Protective degree IP20  Safety Meet the requirement of CE		Mountable method	Wall and rail mountable		
Others  Temperature of the running environment Above 40°C, derate 1% for every additional 1°C.  Altitude <1000m Above 1000m, derate 1% for every additional 100m.  Protective degree IP20  Safety Meet the requirement of CE		Braking unit	Embedded		
Others  environment Above 40°C, derate 1% for every additional 1°C.  Altitude  Altitude Above 1000m, derate 1% for every additional 100m.  Protective degree IP20  Safety Meet the requirement of CE		EMI filter	Optional filter: meet the degree requirement of IEC61800-3 C2, IEC61800-3 C3		
Above 1000m, derate 1% for every additional 100m.  Protective degree IP20  Safety Meet the requirement of CE	Others				
Safety Meet the requirement of CE		Altitude			
		Protective degree	IP20		
Cooling Fan cooling		Safety	Meet the requirement of CE		
		Cooling	Fan cooling		

# / Selection

# Type designation key

# GD20-055G-4-B-EU 1 2 3 4 5

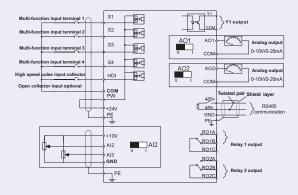
		Detailed description	Detailed content
Abbreviation	1	Product abbreviation	GD20 is short for Goodrive20
Rated power	2	Power range+load type	055-55kW G: constant torque load
Voltage degree	3	Voltage degree	S2: AC 1PH 220V(-15%)-240V(+10%) 2: AC 3PH 220V(-15%)-240V(+10%) 4: AC 3PH 380V(-15%)-440V(+10%)
Additional information 1	4	Braking unit	B: With built-in braking unit for inverters245kW; Standard inverters245kW without built-in braking unit, B is not displayed
Additional information 2	( <del>5</del> )	Special function	EU: built-in Safety Torque Off function; Without EU, without the function

# Rated parameters

Model	Voltage degree	Output power (kW)	Input current (A)	Output current (A)
GD20-0R4G-S2		0.4	6.5	2.5
GD20-0R7G-S2	1PH 220V	0.75	9.3	4.2
GD20-1R5G-S2	IPH 220V	1.5	15.7	7.5
GD20-2R2G-S2		2.2	24	10
GD20-0R4G-2		0.4	3.7	2.5
GD20-0R7G-2		0.75	5	4.2
GD20-1R5G-2		1.5	7.7	7.5
GD20-2R2G-2	3PH 220V	2.2	11	10
GD20-004G-2		4	17	16
GD20-5R5G-2		5.5	21	20
GD20-7R5G-2		7.5	31	30
GD20-0R7G-4		0.75	3.4	2.5
GD20-1R5G-4		1.5	5.0	4.2
GD20-2R2G-4		2.2	5.8	5.5
GD20-004G-4		4	13.5	9.5
GD20-5R5G-4		5.5	19.5	14
GD20-7R5G-4		7.5	25	18.5
GD20-011G-4		11	32	25
GD20-015G-4		15	40	32
GD20-018G-4	3PH 380V	18.5	47	38
GD20-022G-4		22	51	45
GD20-030G-4		30	70	60
GD20-037G-4		37	80	75
GD20-045G-4		45	98	92
GD20-055G-4		55	128	115
GD20-075G-4		75	139	150
GD20-090G-4		90	168	180
GD20-110G-4		110	201	215

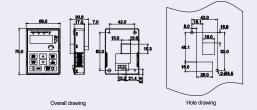
# Standard wiring

### Wiring diagram of control circuit

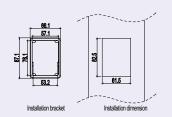


# / Installation dimension

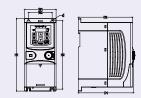
# External keypad dimension



Note: The external keypad can be 20 meters away from the inverter at most.



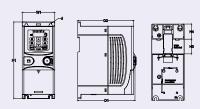
#### Inverter dimensions



Wall mounting of 0.75~2.2kW inverters

#### Dimensions (unit: mm)

Model	W1	W2	H1	H2	D1	D2	Hole (d)
GD20-0R4G-S2	80.0	60.0	160.0	150.0	123.5	120.3	5
GD20-0R7G-S2	80.0	60.0	160.0	150.0	123.5	120.3	5
GD20-1R5G-S2	80.0	60.0	185.0	175.0	140.5	137.3	5
GD20-2R2G-S2	80.0	60.0	185.0	175.0	140.5	137.3	5
GD20-0R4G-2	80.0	60.0	185.0	175.0	140.5	137.3	5
GD20-0R7G-2	80.0	60.0	185.0	175.0	140.5	137.3	5
GD20-0R7G-4	80.0	60.0	185.0	175.0	140.5	137.3	5
GD20-1R5G-4	80.0	60.0	185.0	175.0	140.5	137.3	5
GD20-2R2G-4	80.0	60.0	185.0	175.0	140.5	137.3	5



Rail mounting of inverters of 1PH 220V/3PH 380V (≤2.2kW) and 3PH 220V (≤0.75kW)

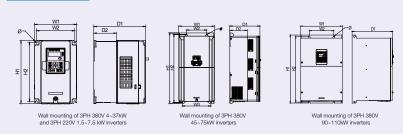
#### Dimensions (unit: mm)

Model	W1	W2	H1	H2	D1	D2	Hole (d)
GD20-0R4G-S2	80.0	160.0	35.4	36.6	123.5	120.3	5
GD20-0R7G-S2	80.0	160.0	35.4	36.6	123.5	120.3	5
GD20-1R5G-S2	80.0	185.0	35.4	36.6	140.5	137.3	5
GD20-2R2G-S2	80.0	185.0	35.4	36.6	140.5	137.3	5
GD20-0R4G-2	80.0	185.0	35.4	36.6	140.5	137.3	5
GD20-0R7G-2	80.0	185.0	35.4	36.6	140.5	137.3	5
GD20-0R7G-4	80.0	185.0	35.4	36.6	140.5	137.3	5
GD20-1R5G-4	80.0	185.0	35.4	36.6	140.5	137.3	5
GD20-2R2G-4	80.0	185.0	35.4	36.6	140.5	137.3	5

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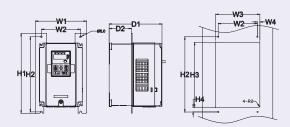
# / Installation dimension

### Inverter dimensions

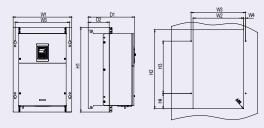


### Dimensions (unit: mm)

Model	W1	W2	W3	H1	H2	D1	D2	Hole (d)
GD20-1R5G-2	146.0	131.0	_	256.0	243.5	167.0	84.5	6
GD20-2R2G-2	146.0	131.0	-	256.0	243.5	167.0	84.5	6
GD20-004G-2	146.0	131.0	-	256.0	243.5	167.0	84.5	6
GD20-5R5G-2	170.0	151.0	_	320.0	303.5	196.3	113.0	6
GD20-7R5G-2	170.0	151.0	_	320.0	303.5	196.3	113.0	6
GD20-004G-4	146.0	131.0	-	256.0	243.5	167.0	84.5	6
GD20-5R5G-4	146.0	131.0	_	256.0	243.5	167.0	84.5	6
GD20-7R5G-4	170.0	151.0	-	320.0	303.5	196.3	113.0	6
GD20-011G-4	170.0	151.0	_	320.0	303.5	196.3	113.0	6
GD20-015G-4	170.0	151.0	_	320.0	303.5	196.3	113.0	6
GD20-018G-4	200.0	185.0	-	340.6	328.6	184.3	104.5	6
GD20-022G-4	200.0	185.0	_	340.6	328.6	184.3	104.5	6
GD20-030G-4	250.0	230.0	_	400.0	380.0	202.0	123.5	6
GD20-037G-4	250.0	230.0	_	400.0	380.0	202.0	123.5	6
GD20-045G-4	282.0	160.0	226.0	560.0	542.0	238.0	138.0	9
GD20-055G-4	282.0	160.0	226.0	560.0	542.0	238.0	138.0	9
GD20-075G-4	282.0	160.0	226.0	560.0	542.0	238.0	138.0	9
GD20-090G-4	338.0	200.0	-	554.0	535.0	329.2	-	9.5
GD20-110G-4	338.0	200.0	_	554.0	535.0	329.2	_	9.5



Flange mounting of 3PH 380V 4~75kW and 3PH 220V 1.5~7.5kW inverters



Flange mounting of 3PH 380V 90~110kW inverters

#### Dimensions (unit: mm)

												_
Model	W1			W4					D1	D2	Hole (d)	
GD20-1R5G-2	170.2	131	150	9.5	292	276	260	6	167	84.5	6	M5
GD20-2R2G-2	170.2	131	150	9.5	292	276	260	6	167	84.5	6	M5
GD20-004G-2	170.2	131	150	9.5	292	276	260	6	167	84.5	6	M5
GD20-5R5G-2	191.2	151	174	11.5	370	351	324	12	196.3	113	6	M5
GD20-7R5G-2	191.2	151	174	11.5	370	351	324	12	196.3	113	6	M5
GD20-004G-4	170.2	131	150	9.5	292	276	260	6	167	84.5	6	M5
GD20-5R5G-4	170.2	131	150	9.5	292	276	260	6	167	84.5	6	M5
GD20-7R5G-4	191.2	151	174	11.5	370	351	324	12	196.3	113	6	M5
GD20-011G-4	191.2	151	174	11.5	370	351	324	12	196.3	113	6	M5
GD20-015G-4	191.2	151	174	11.5	370	351	324	12	196.3	113	6	M5
GD20-018G-4	266	250	224	13	371	250	350.6	20.3	184.6	104	6	M5
GD20-022G-4	266	250	224	13	371	250	350.6	20.3	184.6	104	6	M5
GD20-030G-4	316	300	274	13	430	300	410	55	202	118.3	6	M5
GD20-037G-4	316	300	274	13	430	300	410	55	202	118.3	6	M5
GD20-045G-4	352	332	306	13	580	400	570	80	238	133.8	9	M8
GD20-055G-4	352	332	306	13	580	400	570	80	238	133.8	9	M8
GD20-075G-4	352	332	306	13	580	400	570	80	238	133.8	9	M8
GD20-090G-4	418.5	361	389.5	14.2	600	559	370	108.5	329.5	149.5	9.5	M8
GD20-110G-4	418.5	361	389.5	14.2	600	559	370	108.5	329.5	149.5	9.5	M8
GD20-022G-4	200.0	185.0	_	340.6	328.6	184.3	184.3	104.5	184.3	104.5	6	184.3
GD20-030G-4	250.0	230.0	_	400.0	380.0	202.0	202.0	123.5	202.0	123.5	6	202.0
GD20-037G-4	250.0	230.0	_	400.0	380.0	202.0	202.0	123.5	202.0	123.5	6	202.0
GD20-045G-4	282.0	160.0	226.0	560.0	542.0	238.0	238.0	138.0	238.0	138.0	9	238.0
GD20-055G-4	282.0	160.0	226.0	560.0	542.0	238.0	238.0	138.0	238.0	138.0	9	238.0
GD20-075G-4	282.0	160.0	226.0	560.0	542.0	238.0	238.0	138.0	238.0	138.0	9	238.0
GD20-090G-4	338.0	200.0	-	554.0	535.0	329.2	329.2	_	329.2	-	9.5	329.2
GD20-110G-4	338.0	200.0	_	554.0	535.0	329.2	329.2	_	329.2	_	9.5	329.2

Note: In flange installation mode, the installation bracket is optional

# External LED keypad

Including the external keypads with or without the parameter copying function.



### Filter

Input filter: Control the electromagnetic interference generated from the inverter, please install close to the input terminal side of the inverter.

Output filter: Control the interference from the output side of the inverter, please install close to the output terminals of the inverter.



# Reactor

Input reactor: Improve the power factor of the input side of the inverter and control the higher harmonic current.

Output reactor: Prolong the effective transmitting distance of the inverter and control the sudden high voltage when switching on/off the IGBT of the inverter.



# **Braking resistor**

Auxiliary equipment for braking system, shorten the deceleration time.



# Membrane of heat releasing holes at the side

Apply to severe environment and improve protective effect.

Derate 10% of the machine.







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